## Competitive Routing on a Bounded-Degree Plane Spanner

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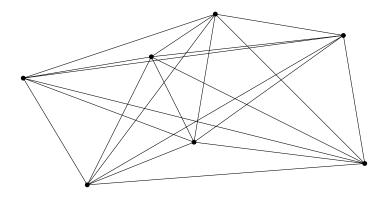
#### Geometric Spanners

Given:

• Set of points in the plane

Goal:

• Approximate the complete Euclidean graph



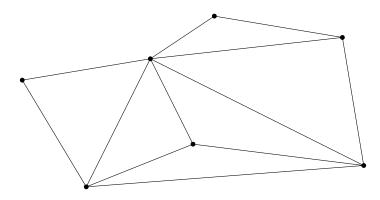
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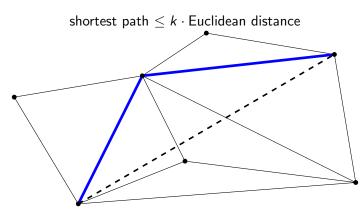


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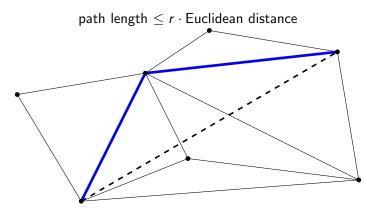
## Competitive Routing

Given:

- Geometric spanner
- Using only local information

Goal:

• Find a short path between any two vertices



Half- $\theta_6$ -graph (Bonichon et al. 2010)

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Bounded-degree variants (Bonichon et al. 2010)

Half- $\theta_6$ -graph (Bonichon et al. 2010)

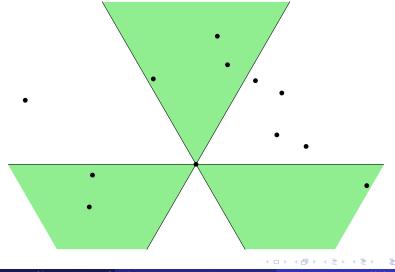
Competitive routing (Bose et al. 2012) Bounded-degree variants (Bonichon et al. 2010)

Half- $\theta_6$ -graph (Bonichon et al. 2010)

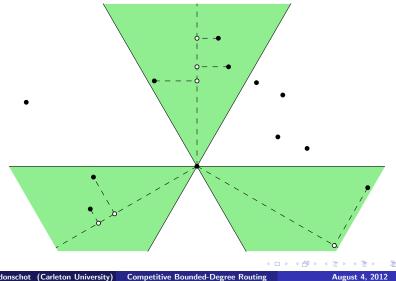
Competitive routing on bounded-degree variants (This result)

Competitive routing (Bose et al. 2012)

• 6 Cones around each vertex: 3 positive, 3 negative

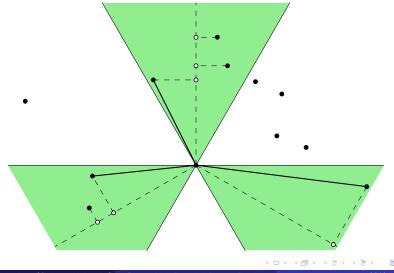


• Connect to 'closest' vertex in each positive cone

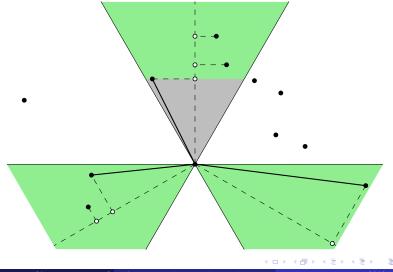


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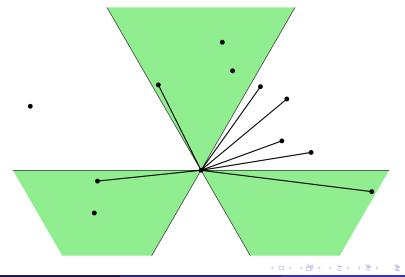
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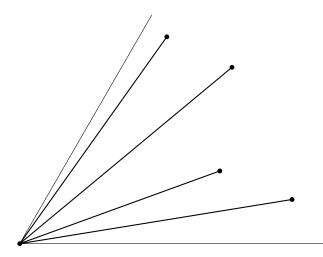
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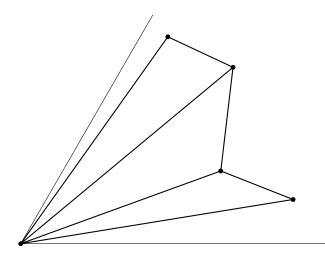
• Negative cones can have unbounded in-degree.



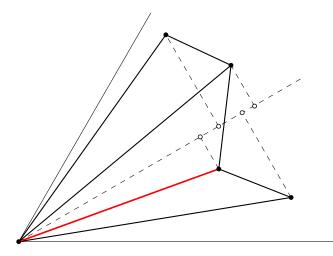
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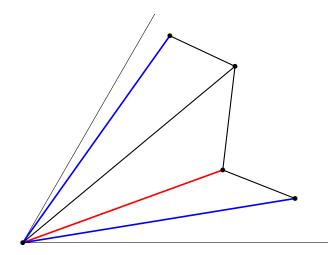
• Consecutive vertices are connected by a *canonical path*.



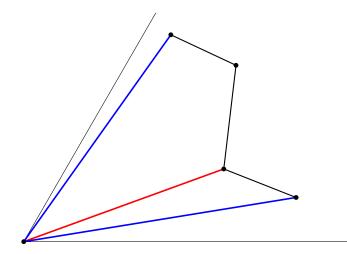
• Keep the edge to the closest vertex...



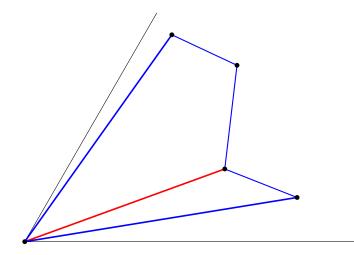
• Keep the edge to the closest vertex and the extreme edges.



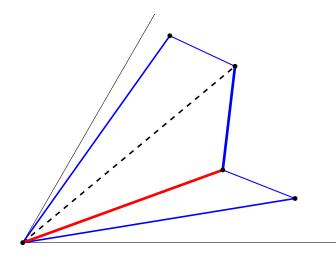
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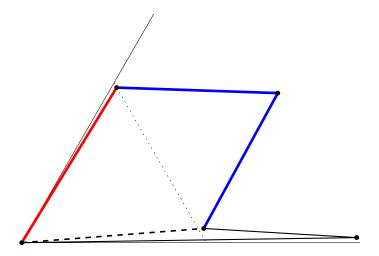
• Edges on the canonical path are always extreme.



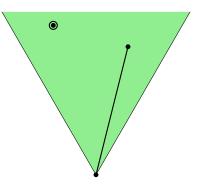
• There is an *approximation path* for every removed edge.



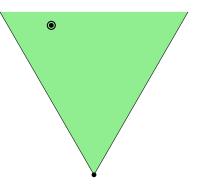
• Result: A 3-spanner of the half- $\theta_6$ -graph.



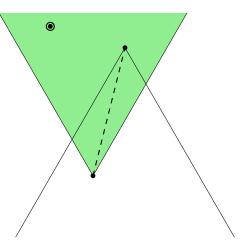
- If t lies in a positive cone:
  - Follow the edge in that cone



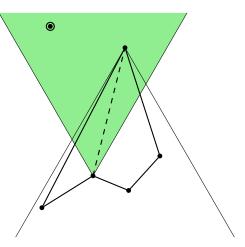
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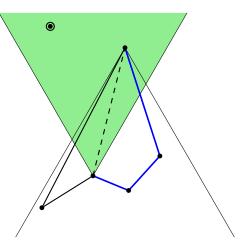
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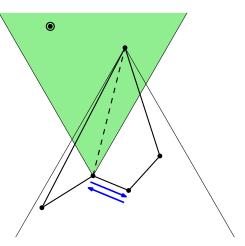
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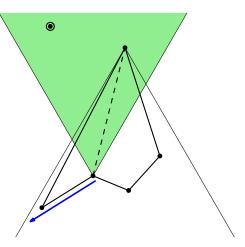
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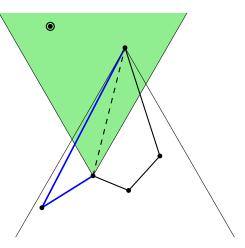
- If t lies in a positive cone:
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- If t lies in a positive cone:
  - Follow the edge in that cone

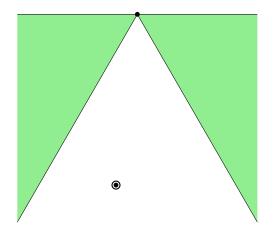


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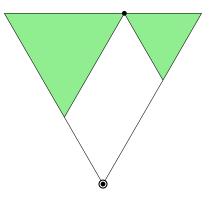
If *t* lies in a negative cone and we did not mark a side yet:

- Follow an edge in that cone
- Follow an edge to the shorter side
- Follow an edge to the longer side and mark the shorter side



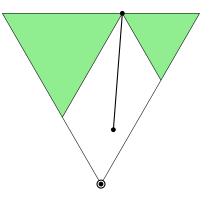
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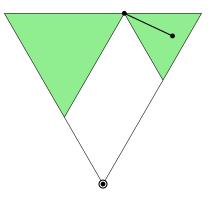
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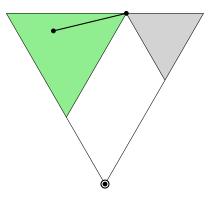
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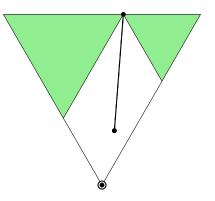
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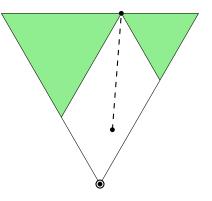
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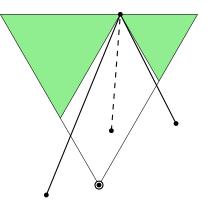
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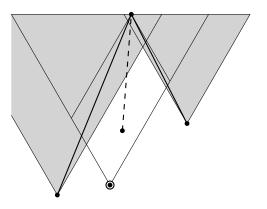
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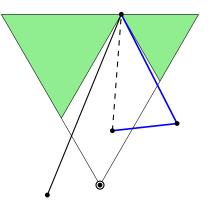
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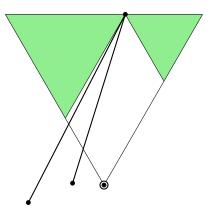
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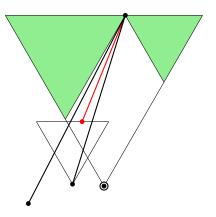
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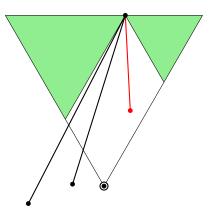
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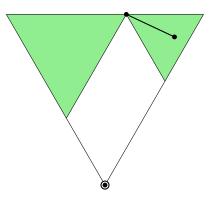
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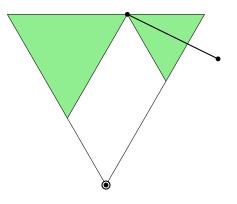
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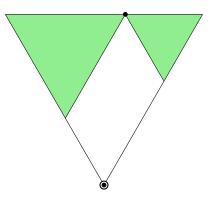
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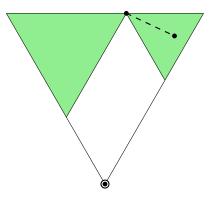
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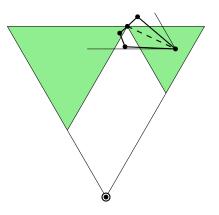
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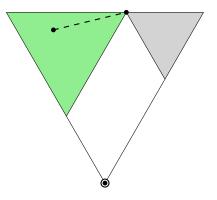
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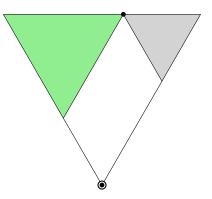
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If *t* lies in a negative cone and we marked a side:

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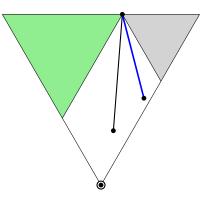
In the half- $\theta_6$ -graph.



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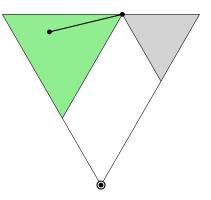
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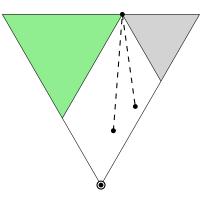
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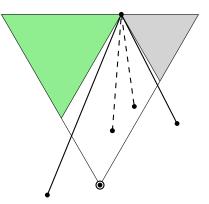
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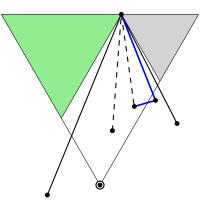
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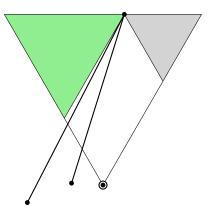
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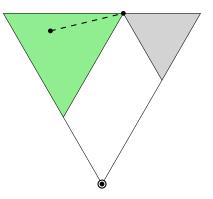
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- Routing ratio can be improved by storing information at vertices.