RNA Secondary Structures

Computational Molecular Biology, COMP 4900/5108. Winter 2006

What is secondary structure?

• Set of canonical $\{AU, CG\}$ basepairs that form via hydrogen bonding when the molecule folds.

They are called Watson-Crick basepairs.

- Also basepair GU is possible.
- Each base forms at most one pair
- Depends on temperature, ionic concentration, presence of metabolites, other environmental factors

What is secondary structure?

- There are three possible representations of secondary structure:
 - graphical,
 - dot-bracket,
 - dot-plot

RNA Graphical and Dot-Bracket Representations



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From Graphical to Dot-Bracket

There is a simple way to convert a Graphical representation to a Dot-bracket representation and vice versa.

- Think of the links in the graphical representation as being formed from elastic band.
- Stretch the *outer opening*, in this case AU, until the whole RNA strand lies flat on a line.
- Stretch the remaining basepairs accordingly.

Stretching: From Graphical to Dot-Bracket



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Dot-Plot Representation

List the bases in a column and a row in the order they occur in the RNA string.



Put a "dot" in positions (i, j), (j, i) if there is a basepair linking bases in positions i and j.



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RNA structures are essential for

- transcriptional and post-transcriptional regulation (iron response elements in UTRs of eukaryote transcripts, micro-RNAs from genomic sequences)
- expression of HIV genes (rev-response element, TAR hairpin)
- mediation of insertion of selenocysteine (RNA structural element prevents translation termination at a UGA codon and instead inserts selenocysteine)
- splicing
- perhaps helps explain 5% of highly-conserved non-genic sequence observed in vertebrates?

Why Study RNA Structure?

Tools to prediction of RNA structure help us

- gain insight on the genome
- shed insight on RNA 3D structure and ultimately function
- better align RNA sequences
- establish phylogenetic relationships among organisms
- design good microarray probes, or RNA molecules for disease therapy

How Many Secondary Structures?

- Forget about A, U, C, G: and number the bases $1 \dots n$.
- Let S(n) be the number of secondary structures for the sequence $1 \dots n$.
- What is S(n)? Well, S(0) = 0.
- From the picture below: S(1) = S(2) = 1 and S(3) = 2.



A Recursive Assumption

- Assume that we know S(k), for all k < n. Can we compute S(n)? There are two cases.
- Either n is not paired with any other element, in which case we count S(n-1) secondary structures. tn-1n Or else n is paired with some other element t < n, n-1n and therefore secondary structures are formed in [1, t-1] and [t+1, n-1].

A Recursive Equation

It follows that S(n) satisfies the recursive equation

$$S(n) = S(n-1) + S(n-2) + S(n-3)S(1) + \dots + S(n-3)S(1)$$

= $S(n-1) + S(n-2) + \sum_{t=2}^{n-2} S(t-1)S(n-1-t)$

- How do you solve this equation and determine S(n)?
- Method uses generating functions! Think of S(n) as the coefficients of a continuous function f(x)

$$y := f(x) = \sum_{n=1}^{\infty} S(n)x^n.$$

• Can you find a *functional* equation satisfied by f(x)?

A Functional Equation

Abbreviate $a_n := S(n)$. Recall that $a_0 = 0, a_1 = a_2 = 1$. We have shown that

$$a_n = a_{n-1} + a_{n-2} + \sum_{t=2}^{n-2} a_{t-1}a_{n-1-t}$$

Multiply both sides of equation by x^n to obtain

$$a_n x^n = x a_{n-1} x^{n-1} + x^2 a_{n-2} x^{n-2} + x^2 \sum_{t=2}^{n-2} x^{t-1} a_{t-1} x^{n-t-1} a_{n-1-t}$$

and take sums of both sides from n = 2 to ∞ and you derive the following equation $y - x = xy + x^2y + x^2y^2$, which implies that

$$x^2y^2 + (x^2 + x - 1)y + x = 0$$

Asymptotic Formula

If we define $F(x, y) := x^2y^2 + (x^2 + x - 1)y + x$ then it follows from Bender's theorem that if (r, s) is the unique solution of the system

$$F(r,s) = r^2 s^2 + (r^2 + r - 1)s + r = 0$$
(1)

$$\frac{\partial F}{\partial y}(r,s) = 2r^2s + r^2 + r - 1 = 0$$
 (2)

then

$$S(n) \sim \sqrt{\frac{rF_x(r,s)}{2\pi F_{yy}(r,s)}} n^{-3/2} r^{-n}.$$
 (3)

It follows that

$$S(n) \sim \sqrt{\frac{15 + 7\sqrt{5}}{8\pi}} n^{-3/2} \left(\frac{3 + \sqrt{5}}{2}\right)^n$$

Secondary Structures with Exactly k Basepairs

Define $S_{n,k}$ as the set of secondary structures on [1, n] with exactly k basepairs.

Let S(n,k) number of secondary structures on [1,n] with exactly k basepairs. So $S(n,k) = |S_{n,k}|$.

Clearly,

$$S(n) = \sum_{k=0}^{\lfloor n/2 \rfloor} S(n,k)$$

and it is easy to show as before that

$$S(n,k) = S(n-1,k) + \sum_{j=1}^{n-2} \sum_{i=0}^{k-1} S(j-1,i)S(n-1-j,k-1-i)$$

Can we compute S(n,k)?

Recursion

• Either n is not paired with any other element, in which case we count S(n-1,k) secondary structures.

• Or else n is paired with some other element t < n. Remove this basepair and you have k - 1 basepairs left.

Then for some $i \leq k-1$, *i* basepairs are formed in [1, t-1] and the remaining k-1-i basepairs in [t+1, n-1].

Equivalence of Trees and Secondary Structures

- A *linear tree* is a rooted tree along with a linear order on the set of children of each vertex.
- Let $T_{n,k}$ the set of unlabeled linear trees with n vertices and n-k leaves.
- Let $T(n,k) := |T_{n,k}|$.



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Poincare Duality: Trees and Secondary Structures

There is a bijection

$$S_{n+k-2,k-1} \to T_{n,k}.$$

The algorithm is as follows:

- 1. Take a member of $S_{n+k-2,k-1}$ in loop form.
- 2. Put a node (the root) of the tree above the figure outside all loops.
- 3. Insert a node inside all loops visible from this node and connect them all to this node.
- 4. Iterate recursively.

Hence,

$$S(n+k-2, k-1) = T(n, k).$$



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Number of Trees

• It can be shown that

$$T(n,k) = \frac{1}{k-1} \binom{n-1}{k} \binom{n-2}{k-2}$$

• A well-known argument is being used here (See L. Lovasz, Comb. Prob. and Exercises, NH, 1979, 4.1 and 4.8): Consider n points u_1, \ldots, u_n and n integers d_1, \ldots, d_n such that $d_1 + \cdots + d_n = 2n - 2$. The number of trees on points u_1, \ldots, u_n in which u_i has degree d_i is given by the formula

$$\frac{(n-2)!}{(d_1-1)!\cdots(d_n-1)!}$$

- Observe that leaves have degree 1.
- Details of the rest of the proof of this are beyond our scope.

Number of Secondary Strauctures

- At least we can use this last formula to derive the number of secondary structures with a given number os basepairs.
- Using the previous bijection

$$S(n,k) = T(n-k+1,k+1)$$
$$= \frac{1}{k} \binom{n-k}{k+1} \binom{n-k+1}{k-1}$$

The reality is far more more complex: individual bases are "linked" with a certain energy!

MFE (minimum free energy) approach

Used to predict secondary structure.

- Hypothesis: an RNA molecule will fold into that secondary structure that minimizes its free energy
- Free energy of a structure (at fixed temperature, ionic concentration) is sum of loop energies
- Tables of loop energies are used to calculate energy of a structure

Given an energy table what is the secondary structure with minimum free energy?

Minimum Free Energy

• Given an energy table, E.g.,

Basepair	-1
Internal Loop	+1.1

• Is this an MFE secondary structure?



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Naive Algorithm

- Naive Algorithm:
 - 1. Enumerate all possible secondary structures;
 - 2. Calculate energy of each;
 - 3. Output that structure which has lowest energy
- Problem: many structures to enumerate! A 50mer could have more than 5000 billion structures
- DP (dynamic programming) algorithm: avoids this problem, but minimizes over restricted structure types

Ruth Nussinov and Ann Jacobson, 1980

- One of the first beautiful ideas in CMB!
- Based on the

"more is less" principle: by calculating more than you need, less work is needed overall

• Construct mfe structure for whole strand from mfe structures for substrands

Minimum Free Energy

• Define

$$\rho(a,b) = \begin{cases} 1 & \text{if } a, b \text{ can basepair} \\ 0 & \text{otherwise} \end{cases}$$

- Given a sequence $a_1 a_2 \cdots a_n$ in $\{A, U, C, G\}^n$ let $X_{i,j}$ be the max number of basepairs in $a_i a_{i+1} \cdots a_j$.
- Observe that $X_{i,j+1}$ is the maximum of $X_{i,j}$ and

$$\max\{(X_{i,l-1} + 1 + X_{l+1,j})\rho(a_l, a_{j+1}) : 1 \le l \le j - 1\}$$

$$i \quad i+1 \quad i+2 \quad l \quad j \quad j+1$$
• Time complexity is $\sum_{i < j \le n} (j - i) \in O(n^3).$

Other Energy Contributions

Problem is in fact much more complex.

Other energy functions contribute to the free energy of $a_1a_2 \cdots a_n$.

- $\alpha(a,b) = \text{free energy of basepair } \{a,b\}$
- $\eta = \text{stacking energy of adjacent basepairs}$
- Destabilization energies
 - $\xi(k) = \text{destabilization free-energy of an end loop of } k$ bases
 - $-\beta(k) =$ destabilization free-energy of bulge of k bases
 - $\gamma(k) = {\rm destabilization}$ free-energy of an interior loop of k bases

Example: Other Energy Contributions



- $\xi(k) = \text{destabilization free-energy of an end loop of } k$ bases
- $\beta(k) =$ destabilization free-energy of bulge of k bases
- $\gamma(k) = \text{destabilization free-energy of an interior loop of } k$ bases

MFE for Hairpin Loops

 $H_{i,j}$ is min free energy single hairpin structure on $a_i a_{i+1} \cdots a_j$, for i < j, where a_i and a_j basepair and there is a single end loop. If a_i and a_j cannot basepair set $H_{i,j} = \infty$. $H_{i,j}$ is minimum of five quantities. (a) End Loop: $\alpha(a_i, a_j) + \xi(j - i + 1)$ (b) Helix Extension (stacking bps): $\alpha(a_i, a_j) + \eta + H_{i+1,j-1}$ *i i*+1 j-1



Computation Time

Time Complexity is $O(n^4)$. Why?

Take each of the five steps previously described.

• Steps (a) & (b):

$$\sum_{1 \le i < j \le n} 1 \in O(n^2)$$

• Steps (c) & (d):

$$\sum_{1 \le i < j \le n} (j-i) \in O(n^3)$$

• Step (e):

$$\sum_{1 \le i < j \le n} \left(\sum_{i' \le i < j \le j'} 1 \right) \in O(n^4)$$

Dynamic Programming

• Construct a matrix $(H_{i,j})$:

	a_n	a_{n-1}	• • •	a_2	a_1
a_1	$H_{1,n}$	$H_{1,n-1}$	• • •	$H_{1,2}$	$H_{1,1}$
a_2	$H_{2,n}$	$H_{2,n-1}$	• • •	$H_{2,2}$	
• •	• •	• •			
a_{n-1}	$H_{n-1,n}$	$H_{n-1,n-1}$			
a_n	$H_{n,n}$				

- If a_i and a_j cannot basepair set $H_{i,j} = \infty$.
- If a_i and a_j can be a sepair and $j i 1 \ge m$ (*m* is the min endloop size) $H_{i,j}$ to the value computed before.

Dynamic Programming: Reducing Computation Time

Note that interior loops must be of size $\geq m$, for some value m. Now $H_{i,j}$ results from the five situations:

- End Loop: $\alpha(a_i, a_j) + \xi(j i + 1)$
- Helix Extension: $\alpha(a_i, a_j) + \eta + H_{i+1,j-1}$
- **Bulge:** $\min_{k\geq 1} \{ \alpha(a_i, a_j) + \beta(k) + H_{i+k+1, j-1} \}$
- **Bulge:** $\min_{k\geq 1} \{ \alpha(a_i, a_j) + \beta(k) + H_{i+1, j-k-1} \}$
- Interior Loop: $\min_{l,k\geq 1} \{\alpha(a_i,a_j) + \gamma(l,k) + H_{i+l+1,j-k-1}\}$

Reducing Computation Time to $O(n^3)$

- Given a pair (i, j), consider the set of candidate positions $Cd(i, j) = \{(k, l) : l - k - 1 \ge m, k \ge i + 2, j - 2 \ge l\}$
- The interior loop has size s = (j - i - 1) - (l - k + 1) = (j - i) - (l - k) - 2
- Along lines such that l k = constant the interior loop destabilization function $\gamma(s)$ is constant.
- For each pair (i, j) store the values $H_{i,j}^*(s) := \min\{H_{k,l} : (k, l) \in Cd(i, j)\&s = (j - i) - (l - k) - 2\}$
- When moving from j i = c to j i = c + 1 each vector can be updated in time O(n).
- Best interior loop: $\min\{\alpha(a_i, b_j) + \gamma((j-i) (k-l)) + H_{i,j}^*(s)\}$